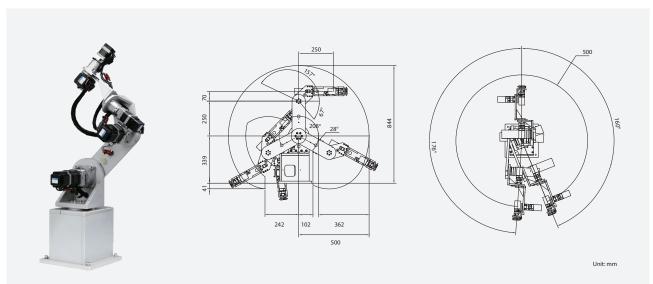
# **MiniBOT Robot**



# Main Features

- EtherCAT-based
- Compact design
- Suitable for education
- Standard 6-axis articulated robot

# **Contents**

- Control cabinet
- Robot control API
- Articulated 6-axis robot
- Open robot controller

### **Product Overview**

#### **EtherCAT Communication**

Based on standard EtherCAT communication, MiniBOT provides an expandable distributed control system. It is also a good material for EtherCAT-related training.

#### Industrial Robot Design

By referring to design of general industrial 6-axis articulated robots, MiniBOT is built in the same concept. Its nude mechanical architecture makes it easy to learn the structure of an industrial robot.

#### Open Development Environment

MiniBOT comes with a utility tool to directly operate the robot. Robotic control APIs are also provided in Windows platform, so that users can leverage its openness to develop any kind of robot applications.

# **Specifications**

#### Robot Arm

- Degree of freedom: 6
- Payload: 1kg
- Driving system: EtherCAT close-loop stepper
- Position feedback: incremental encoder
- Operation range: 595mm (maximum) Hardware limit:
  - J1: 336°(+176° ~ -160°)
  - J2: 236°(+208° ~ -28°)
  - J3: 224°(+157° ~ -67°)
  - J4: 319°(+184° ~ -135°)
  - J5: 257°(+129° ~ -128°)
  - J6: 720°(+360° ~ -360°)
- Repeatability: ±0.12mm
- Weight: arm 30kg
- Input voltage: single phase 100~240Vac

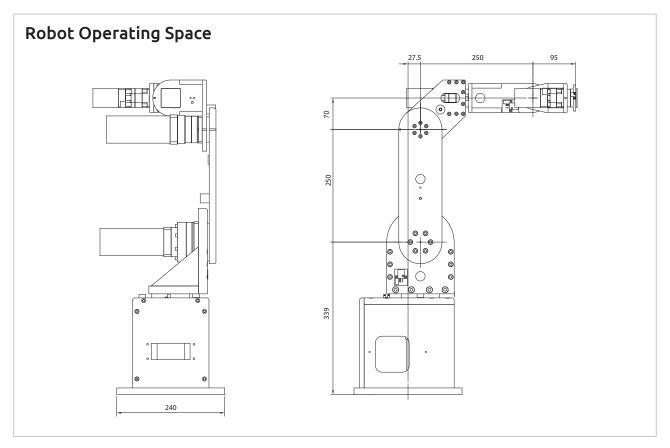
#### Controller

- DI/O: 15-ch DI/16-ch DO (DB37 connector)
- 1 x Intel® GbE LAN port
- 1 x VGA
- 2 x USB 2.0 (external)
- 1 x USB 3.0, 1 x USB 2.0 (inside cabinet)
- 1 x Emergency stop bottom
- Weight: control cabinet 20kg

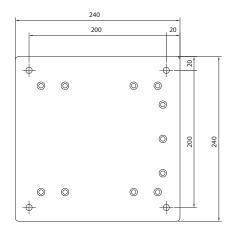
## Software

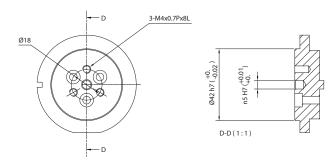
- NexGRC runtime (robot control runtime)
- NexMotion studio (configuration utility)
- Provide standard robot motion control functions
- Support C\C++, C# and VB.Net for user programming
- OS: WES7





# **Installation**





# **Ordering Information**

## **Robot Package**

• MiniBOT robot package (P/N: 7900000179X00)

#### Optional

- Robot stand (P/N: 790000180X00) 70 x 70 x 78 (cm)
- Robot stand (P/N: 7900000183X00) 80 x 80 x 78 (cm)
- Gripper package (P/N: 7900000181X00)
- Terminal board package (P/N: 7900000182X00) 2m and DB-37 terminal board

NEXCOBOT MiniBOT Robot